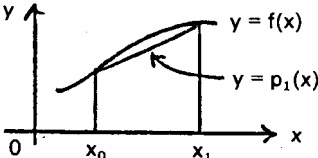


**UNIT 14: Interpolation and Lagrange Interpolating Polynomials**

Specific Objectives:

1. To learn the concept of interpolation.
2. To learn Lagrange Interpolating Polynomial.
3. To apply Lagrange Interpolating Polynomial to approximate functions, and estimate the errors.

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Detailed Content	Time Ratio	Notes on Teaching
14.1 Interpolation and Interpolating Polynomials	1	<p>Students are expected to know the meaning of interpolation: Interpolation involves estimating the values of a function <math>f(x)</math> for arguments between <math>x_0, x_1, \dots, x_n</math> at which the values <math>f(x_0), f(x_1), \dots, f(x_n)</math> are known.</p> <p>They are also expected to know that approximation by polynomial is one of the most heavily used in numerical methods. A polynomial <math>p(x)</math> is used as a substitute for the function <math>f(x)</math> because polynomials are easy to compute, only simple integral powers being involved; their derivatives and integrals are found without much difficulty and are themselves polynomials; roots of polynomial equations are also easy to locate.</p>
14.2 Construction of Lagrange Interpolating Polynomials	3	<p>As an introduction, teachers may demonstrate Lagrange Interpolating Polynomial (L.I.P.), <math>p_n(x)</math> for <math>n = 1</math>. A graph as shown below may be used to give students a physical meaning.</p>  <p>Students should have no problem to see that they are just asked to approximate the curve <math>y = f(x)</math> in between <math>x_0</math> and <math>x_1</math> by the polynomial <math>p_1(x) = a_1x + a_0</math>.</p>

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Detailed Content	Time Ratio	Notes on Teaching										
14.3 Use of Lagrange Interpolating Polynomial	2	<p>Clearly, <math>p_1(x_0) = f(x_0)</math>, <math>p_1(x_1) = f(x_1)</math> and <math>p_1(x) = a_1x + a_0</math>.</p> <p>We have <math>p_1(x) - a_1x - a_0 = 0</math>  <math>f(x_0) - a_1x_0 - a_0 = 0</math>  <math>f(x_1) - a_1x_1 - a_0 = 0</math>.</p> <p>Eliminating <math>a_0</math> and <math>a_1</math>, we get</p> $p_1(x) = f(x_0) \frac{x - x_1}{x_0 - x_1} + f(x_1) \frac{x - x_0}{x_1 - x_0}$ <p>Similarly, teachers may proceed with the aid of a graph like that above to derive the second-degree L.I.P. and obtain</p> $p_2(x) = f(x_0) \frac{(x - x_1)(x - x_2)}{(x_0 - x_1)(x_0 - x_2)} + f(x_1) \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)} + f(x_2) \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)}$ <p>In a similar manner the third-degree polynomial can also be deduced. For students' interest, the term 'Lagrange Multiplier Function' may be introduced.</p> <p>Finally, teachers could help students to draw the conclusion that <math>p_n(x)</math>, <math>n = 1, 2, 3</math>, is of degree <math>n</math> and that <math>p_n(x_i) = f(x_i)</math> at the <math>n + 1</math> tabulated points <math>x_i</math>. The extension of this fact to the general case is not a necessity.</p> <p>The use of L.I.P. should be demonstrated with examples.</p> <p><i>Example 1</i>              Given the four values of an unknown function at 0, 1, 2, 4 as shown in the table.</p> <table border="1" data-bbox="933 2011 1225 2067"> <tr> <td><math>x_k</math></td> <td>0</td> <td>1</td> <td>2</td> <td>4</td> </tr> <tr> <td><math>y_k</math></td> <td>1</td> <td>1</td> <td>2</td> <td>5</td> </tr> </table>	$x_k$	0	1	2	4	$y_k$	1	1	2	5
$x_k$	0	1	2	4								
$y_k$	1	1	2	5								

Detailed Content	Time Ratio	Notes on Teaching														
14.4 Error Estimation of Interpolating Polynomial	3	<p>The L.I.P. of degree 3 is <math>p_3(x) = \frac{1}{12}(-x^3 + 9x^2 - 8x + 12)</math>. Students may also be required to evaluate some functional values for arguments lying between <math>x = 0</math> and <math>x = 4</math>.</p> <p><i>Example 2</i> Using the data in the table</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td><math>v</math></td> <td>10</td> <td>15</td> <td>22.5</td> <td>33.75</td> <td>50.625</td> <td>75.937</td> </tr> <tr> <td><math>y</math></td> <td>0.300</td> <td>0.675</td> <td>1.519</td> <td>3.417</td> <td>7.689</td> <td>17.300</td> </tr> </table> <p>students may be required to apply L.I.P. to find the value of <math>p</math> corresponding to <math>v = 21</math> using various degrees of the L.I.P. chosen (<math>p = 1.350</math> for <math>n = 1</math> and <math>p = 1.323</math> for <math>n = 2</math>). From this example, students should be able to realize that using the same number of different neighbouring points would yield different results.</p> <p>For further illustration in class, common functions like sine and cosine functions are worth demonstrating. Intermediate functional values estimated using L.I.P. could be compared to actual values from a calculator. More interesting problems could be obtained by selecting a given table of data relating to an economic trend or the population of a country in a period and students are asked to estimate some missing data.</p> <p>At this stage, teachers should remind students that L.I.P. is only a method of polynomial interpolation and that many other methods exist. For the abler students teachers may discuss with them the uniqueness of the interpolating polynomial.</p> <p>To begin error estimation, teachers may introduce the function <math>\pi(x) = (x - x_0)(x - x_1)(x - x_2)(x - x_3)</math>, which may be used to express the coefficients of <math>f(x_i)</math>, i.e. <math>\frac{\pi(x_i)}{(x - x_i)\pi'(x_i)}</math> in a given L.I.P., in a more compact form, as</p>	$v$	10	15	22.5	33.75	50.625	75.937	$y$	0.300	0.675	1.519	3.417	7.689	17.300
$v$	10	15	22.5	33.75	50.625	75.937										
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Detailed Content	Time Ratio	Notes on Teaching								
	9	$p_n(x) = \sum_{i=0}^n f(x_i) \frac{\pi(x_i)}{(x - x_i)\pi'(x_i)}, \quad n = 1, 2, 3.$ <p>By defining the error <math>e(x) = f(x) - p_n(x) = C\pi(x)</math>, where <math>C</math> is a constant, and constructing the function <math>F(x) = f(x) - p_n(x) - C\pi(x)</math> and choosing <math>x = \bar{x}</math> (where <math>x_0 \leq \bar{x} \leq x_n</math> and <math>\bar{x} \neq x_i, i = 0, 1, 2, 3</math>), students could be led to apply Rolle's theorem repeatedly to arrive at</p> $e(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} \pi(x) \quad \text{where } \xi \text{ lies in the tabulated interval.}$ <p>Students should then realize that if <math>f^{(n+1)}(\xi)</math> has an upperbound for <math>\xi</math> in the interval containing the tabulated points, say <math>M = \max  f^{(n+1)}(\xi) </math>, then the absolute error is given by <math> e(x)  \leq \left  M \frac{\pi(x)}{(n+1)!} \right </math>.</p> <p>Examples should be provided for illustration. The following is one such example.</p> <p><i>Example</i> Given the function <math>f(x) = \sin \frac{\pi x}{2}</math> takes the following values in the table</p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td><math>x_k</math></td> <td>0</td> <td>1</td> <td>2</td> </tr> <tr> <td><math>y_k</math></td> <td>0</td> <td>1</td> <td>0</td> </tr> </table> <p>students may be required to show that <math> e(x)  \leq \left  \frac{\pi^3}{8} x(x-1)(x-2) \right </math> and then to compute this estimate at <math>x = 0.5</math> and compare it with the actual error.</p>	$x_k$	0	1	2	$y_k$	0	1	0
$x_k$	0	1	2							
$y_k$	0	1	0							